


Oscillations in non-autonomous systems

1109

Linear systems with periodic forcing.


$$f(t) = f_0 \cos \omega t$$

harmonic oscillator. Energy is not conserved (time dependence)

$$m\ddot{x} + kx = f_0 \cos \omega t \Rightarrow \ddot{x} + \omega^2 x = a \cos \omega t$$

$$\omega^2 = \frac{k}{m}, \quad a = \frac{f_0}{m}$$

Prop A general solution is obtained as

$$x(t) = x_p(t) + x_a(t)$$

where $x_p(t)$ is (any) particular solution and $x_a(t)$ is a ^{general} solution of the autonomous system with $a=0$.

Proof If $x_1(t)$ and $x_2(t)$ are solutions, then

$$\ddot{x}_i + \omega^2 x_i = f_0 \cos \omega t, \quad i=1,2$$

$$0 \Rightarrow (\ddot{x}_1 - \ddot{x}_2) + \omega^2 (x_1 - x_2) = 0$$

for any $x(t) = x_p(t) + x_a(t)$, we have

$$\ddot{x} + \omega^2 x = \underbrace{\ddot{x}_p + \omega^2 x_p}_{f_0 \cos \omega t} + \underbrace{\ddot{x}_a + \omega^2 x_a}_0 = f_0 \cos \omega t$$

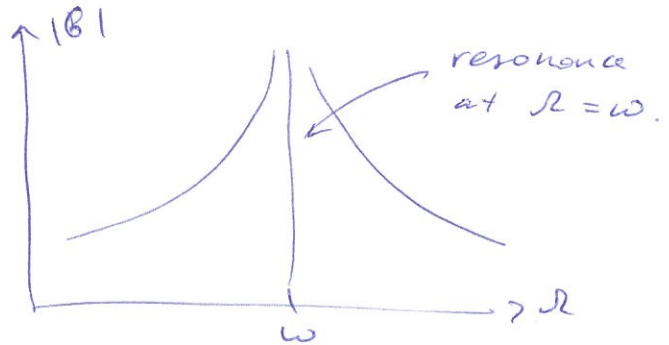
General solution: $x_a(t) = c \cos(\omega t + \varphi)$

for any $c \in \mathbb{R}$, $\varphi \in S^1$

Particular solution: $x_p = b \cos \Omega t$

$$\Rightarrow -b \Omega^2 \cos \Omega t + b \omega^2 \cos \Omega t = a \cos \Omega t$$

$$\Rightarrow b = \frac{a}{\omega^2 - \Omega^2}$$



Oscillations near the resonance from the rest:

$$x(0) = 0, \quad \dot{x}(0) = 0.$$

$$x(t) = a \cos(\omega t + \varphi) + b \cos \Omega t,$$

$\Omega = \omega + \varepsilon, \quad \varepsilon \ll \omega.$

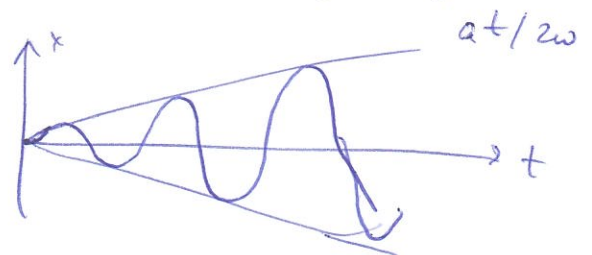
$$b \cos \Omega t = \frac{a}{\omega^2 - \Omega^2} \cos \Omega t = \frac{a}{\omega^2 - (\omega + \varepsilon)^2} \cos((\omega + \varepsilon)t)$$

$$= -\frac{a}{2\omega\varepsilon + \varepsilon^2} \left(\underbrace{\cos \omega t}_{1 + o(\varepsilon)} \underbrace{\cos \varepsilon t}_{\varepsilon t + o(\varepsilon)} - \sin \omega t \sin \varepsilon t \right)$$

$$\approx -\frac{a}{2\omega\varepsilon} (\cos \omega t - \varepsilon t \sin \omega t)$$

↳ can be merged with $a \cos(\omega t + \varphi)$

$$\Rightarrow x(t) \approx \frac{a}{2\omega} + \sin \omega t$$



Valid for $\varepsilon t \ll 1 \Rightarrow t \ll \frac{1}{\varepsilon}$

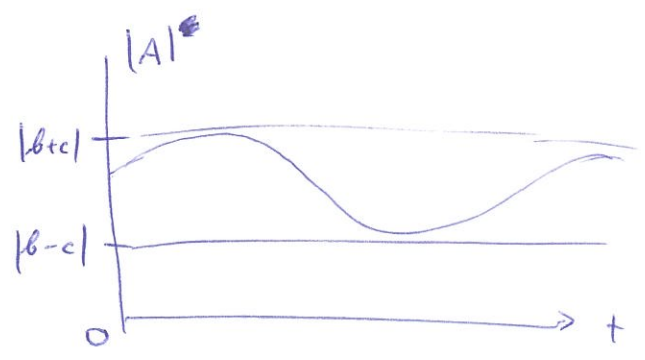
For large times:

$$\begin{aligned}
 x(t) &= \underbrace{c \cos(\omega t + \varphi)}_{x_a} + \underbrace{b \cos((\omega + \varepsilon)t)}_{x_p} \\
 &= \operatorname{Re} \left[c e^{i(\omega t + \varphi)} + b e^{i(\omega + \varepsilon)t} \right] = \operatorname{Re} \left[\underbrace{c e^{i\varphi} + b e^{i\varepsilon t}}_{A(t) e^{i\varphi(t)}} \right] e^{i\omega t} \\
 &= A(t) \operatorname{Re} e^{i(\omega t + \varphi(t))} = \underline{A(t) \cos(\omega t + \varphi(t))}
 \end{aligned}$$

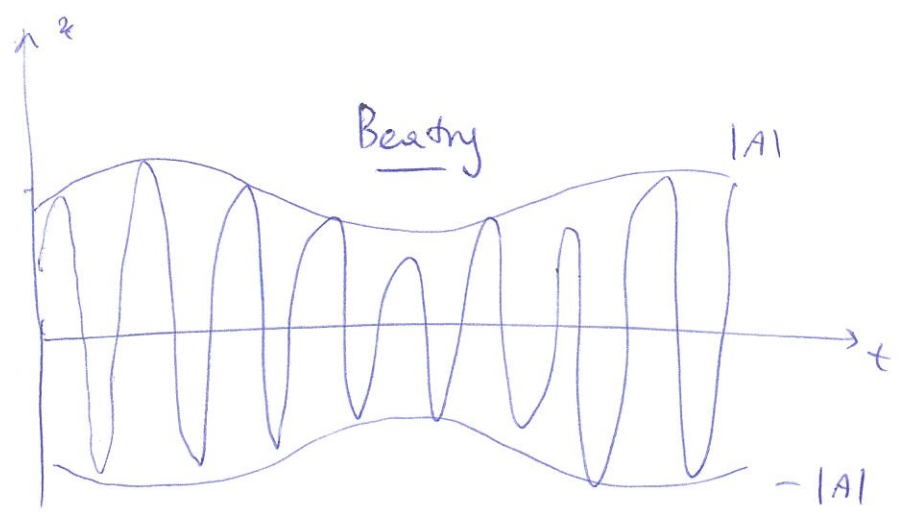
Functions $A(t)$ and $\varphi(t)$ are slow (depend on εt).

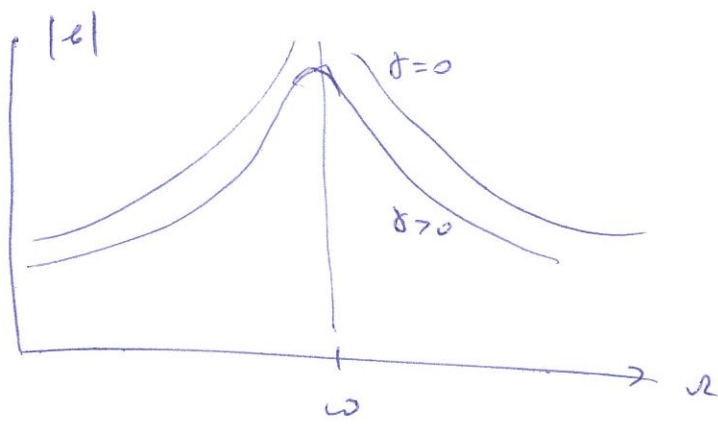
$$\begin{aligned}
 |A|^2 &= |c e^{i\varphi} + b e^{i\varepsilon t}|^2 = (c \cos \varphi + b \cos \varepsilon t)^2 + (c \sin \varphi + b \sin \varepsilon t)^2 \\
 &= c^2 + b^2 + 2bc (\cos \varphi \cos \varepsilon t + \sin \varphi \sin \varepsilon t) = \\
 &= c^2 + b^2 + 2bc \cos(\varepsilon t - \varphi).
 \end{aligned}$$

$$\Rightarrow |b-c| \leq |A| \leq |b+c|$$



Final ~~solution~~ form of solution:





$$|z| = \frac{|a|}{\sqrt{(\omega^2 - \Omega^2)^2 + 4\delta^2 \Omega^2}}$$

System with n degrees of freedom.

Small forced oscillations (linearized system)

$$M\ddot{x} + Cx = f_0 \cos \Omega t \quad M = M^T > 0, \quad c = c^T.$$

$$x = q - q_0 \in \mathbb{R}^n, \quad f_0 \in \mathbb{R}^n,$$

Consider a stable system: $C > 0$.

General solution $x(t) = \underbrace{x_p(t)}_{\text{particular}} + \underbrace{x_a(t)}_{\text{general autonomous (} f_0 = 0)}$

$$x_a(t) = \sum_{i=1}^n c_i u_i \cos(\omega_i t + \varphi_i), \quad u_i \in \mathbb{R}^n$$

$$(-\omega_i^2 M + C)u_i = 0$$

$$(\lambda^2 = -\omega^2)$$

Obtained

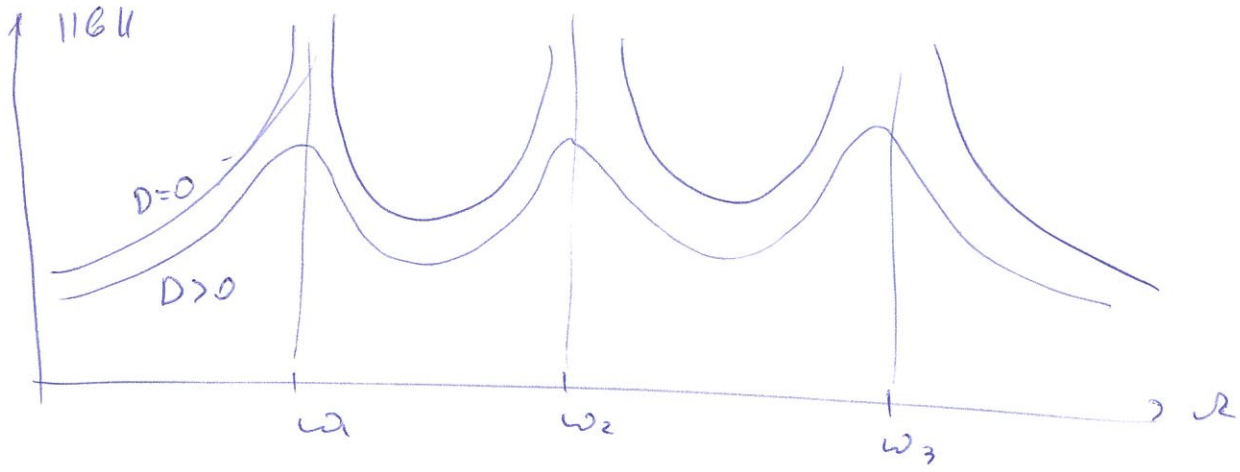
Assume $x_p = b \cos \Omega t, \quad b \in \mathbb{R}^n$

$$[-\Omega^2 M + C] b \cos \Omega t = f_0 \cos \Omega t$$

$$b = [-\Omega^2 M + C]^{-1} f_0 \quad \text{if} \quad \det(-\Omega^2 M + C) \neq 0$$

Resonances: $\Omega^2 \approx \omega_i^2$.

$\Omega^2 \neq \omega_i^2$ for all i .



System with dissipation: $M\ddot{x} + D\dot{x} + Cx = f_0 \cos \omega t$
 $D = D^T > 0.$

Complex form: $M\ddot{x} + D\dot{x} + Cx = f_0 e^{i\omega t}$ } Real solution is $\text{Re}(b e^{i\omega t})$.
 $x = b e^{i\omega t}, b \in \mathbb{C}^n$

$$\Rightarrow [-\omega^2 M + i\omega D + C] b e^{i\omega t} = f_0 e^{i\omega t}$$

Note that $\det [-\omega^2 M + i\omega D + C] \neq 0$ for any $\omega \in \mathbb{R}$
 (we proved that $\text{Re} \lambda < 0$ for any $\lambda = i\omega$ ~~all the~~
 satisfying the charact. eq. $\det [\lambda^2 M + \lambda D + C] = 0$)

$$\Rightarrow b = [-\omega^2 M + i\omega D + C]^{-1} f_0$$

General solution is $x(t) = x_p(t) + x_a(t)$ and

$x_a(t) \rightarrow 0$ as $t \rightarrow \infty$ (asymptotic stability).

Hence $x(t) \rightarrow x_p(t) = \text{Re}(b e^{i\omega t}) =$
 $= \text{Re} b \cos \omega t + \text{Im} b \sin \omega t.$